

MC33178, MC33179

Low Power, Low Noise Operational Amplifiers

The MC33178/9 series is a family of high quality monolithic amplifiers employing Bipolar technology with innovative high performance concepts for quality audio and data signal processing applications. This device family incorporates the use of high frequency PNP input transistors to produce amplifiers exhibiting low input offset voltage, noise and distortion. In addition, the amplifier provides high output current drive capability while consuming only 420 μ A of drain current per amplifier. The NPN output stage used, exhibits no deadband crossover distortion, large output voltage swing, excellent phase and gain margins, low open-loop high frequency output impedance, symmetrical source and sink AC frequency performance.

The MC33178/9 family offers both dual and quad amplifier versions, and is available in DIP and SOIC packages.

- 600 Ω Output Drive Capability
- Large Output Voltage Swing
- Low Offset Voltage: 0.15 mV (Mean)
- Low T.C. of Input Offset Voltage: 2.0 μ V/ $^{\circ}$ C
- Low Total Harmonic Distortion: 0.0024% (@ 1.0 kHz w/600 Ω Load)
- High Gain Bandwidth: 5.0 MHz
- High Slew Rate: 2.0 V/ μ s
- Dual Supply Operation: \pm 2.0 V to \pm 18 V
- ESD Clamps on the Inputs Increase Ruggedness without Affecting Device Performance

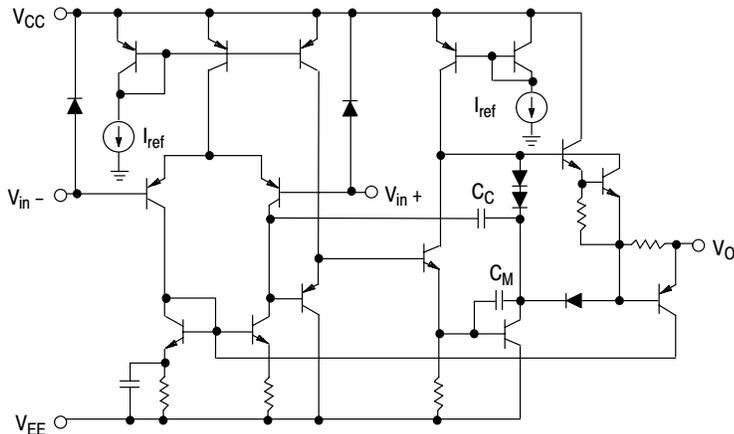


Figure 1. Representative Schematic Diagram
(Each Amplifier)

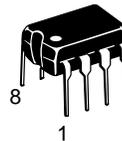


ON Semiconductor®

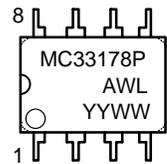
<http://onsemi.com>

MARKING DIAGRAMS

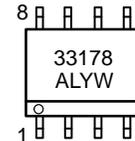
DUAL



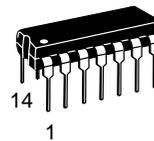
PDIP-8
P SUFFIX
CASE 626



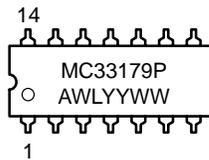
SO-8
D SUFFIX
CASE 751



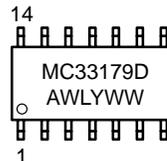
QUAD



PDIP-14
P SUFFIX
CASE 646



SO-14
D SUFFIX
CASE 751A



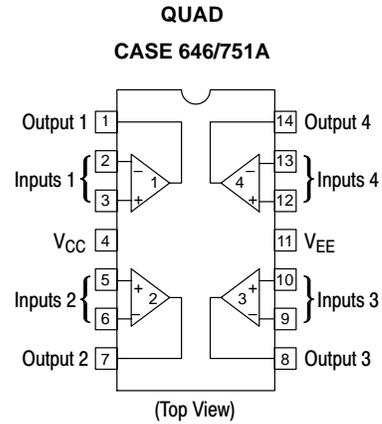
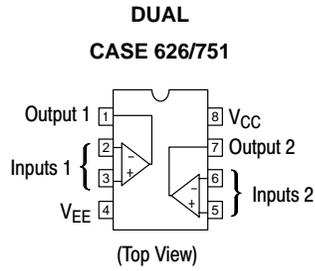
A = Assembly Location
WL, L = Wafer Lot
YY, Y = Year
WW, W = Work Week

ORDERING INFORMATION

Device	Package	Shipping
MC33178D	SO-8	98 Units/Rail
MC33178DR2	SO-8	2500 Tape & Reel
MC33178P	PDIP-8	50 Units/Rail
MC33179D	SO-14	55 Units/Rail
MC33179DR2	SO-14	2500 Tape & Reel
MC33179P	PDIP-14	25 Units/Rail

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PIN CONNECTIONS



MAXIMUM RATINGS

Rating	Symbol	Value	Unit
Supply Voltage (V_{CC} to V_{EE})	V_S	+36	V
Input Differential Voltage Range	V_{IDR}	Note 1	V
Input Voltage Range	V_{IR}	Note 1	V
Output Short Circuit Duration (Note 2)	t_{SC}	Indefinite	sec
Maximum Junction Temperature	T_J	+150	°C
Storage Temperature Range	T_{stg}	-60 to +150	°C
Maximum Power Dissipation	P_D	Note 2	mW
Operating Temperature Range	T_A	-40 to +85	°C

1. Either or both input voltages should not exceed V_{CC} or V_{EE} .
2. Power dissipation must be considered to ensure maximum junction temperature (T_J) is not exceeded. (See power dissipation performance characteristic, Figure 2.)

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DC ELECTRICAL CHARACTERISTICS ($V_{CC} = +15\text{ V}$, $V_{EE} = -15\text{ V}$, $T_A = 25^\circ\text{C}$, unless otherwise noted.)

Characteristics	Figure	Symbol	Min	Typ	Max	Unit
Input Offset Voltage ($R_S = 50\ \Omega$, $V_{CM} = 0\text{ V}$, $V_O = 0\text{ V}$) ($V_{CC} = +2.5\text{ V}$, $V_{EE} = -2.5\text{ V}$ to $V_{CC} = +15\text{ V}$, $V_{EE} = -15\text{ V}$) $T_A = +25^\circ\text{C}$ $T_A = -40^\circ$ to $+85^\circ\text{C}$	3	$ V_{IO} $	– –	0.15 –	3.0 4.0	mV
Average Temperature Coefficient of Input Offset Voltage ($R_S = 50\ \Omega$, $V_{CM} = 0\text{ V}$, $V_O = 0\text{ V}$) $T_A = -40^\circ$ to $+85^\circ\text{C}$	3	$\Delta V_{IO}/\Delta T$	–	2.0	–	$\mu\text{V}/^\circ\text{C}$
Input Bias Current ($V_{CM} = 0\text{ V}$, $V_O = 0\text{ V}$) $T_A = +25^\circ\text{C}$ $T_A = -40^\circ$ to $+85^\circ\text{C}$	4, 5	I_{IB}	– –	100 –	500 600	nA
Input Offset Current ($V_{CM} = 0\text{ V}$, $V_O = 0\text{ V}$) $T_A = +25^\circ\text{C}$ $T_A = -40^\circ$ to $+85^\circ\text{C}$		$ I_{IO} $	– –	5.0 –	50 60	nA
Common Mode Input Voltage Range ($\Delta V_{IO} = 5.0\text{ mV}$, $V_O = 0\text{ V}$)	6	V_{ICR}	–13 –	–14 +14	– +13	V
Large Signal Voltage Gain ($V_O = -10\text{ V}$ to $+10\text{ V}$, $R_L = 600\ \Omega$) $T_A = +25^\circ\text{C}$ $T_A = -40^\circ$ to $+85^\circ\text{C}$	7, 8	A_{VOL}	50 25	200 –	– –	kV/V
Output Voltage Swing ($V_{ID} = \pm 1.0\text{ V}$) ($V_{CC} = +15\text{ V}$, $V_{EE} = -15\text{ V}$) $R_L = 300\ \Omega$ $R_L = 300\ \Omega$ $R_L = 600\ \Omega$ $R_L = 600\ \Omega$ $R_L = 2.0\text{ k}\Omega$ $R_L = 2.0\text{ k}\Omega$ ($V_{CC} = +2.5\text{ V}$, $V_{EE} = -2.5\text{ V}$) $R_L = 600\ \Omega$ $R_L = 600\ \Omega$	9, 10, 11	V_{O+} V_{O-} V_{O+} V_{O-} V_{O+} V_{O-} V_{O+} V_{O-}	– – +12 – +13 – – –	+12 –12 +13.6 –13 +14 –13.8 1.6 –1.6	– – – –12 – –13 – –1.1	V
Common Mode Rejection ($V_{in} = \pm 13\text{ V}$)	12	CMR	80	110	–	dB
Power Supply Rejection $V_{CC}/V_{EE} = +15\text{ V}/-15\text{ V}$, $+5.0\text{ V}/-15\text{ V}$, $+15\text{ V}/-5.0\text{ V}$	13	PSR	80	110	–	dB
Output Short Circuit Current ($V_{ID} = \pm 1.0\text{ V}$, Output to Ground) Source ($V_{CC} = 2.5\text{ V}$ to 15 V) Sink ($V_{EE} = -2.5\text{ V}$ to -15 V)	14, 15	I_{SC}	+50 –50	+80 –100	– –	mA
Power Supply Current ($V_O = 0\text{ V}$) ($V_{CC} = 2.5\text{ V}$, $V_{EE} = -2.5\text{ V}$ to $V_{CC} = +15\text{ V}$, $V_{EE} = -15\text{ V}$) MC33178 (Dual) $T_A = +25^\circ\text{C}$ $T_A = -40^\circ$ to $+85^\circ\text{C}$ MC33179 (Quad) $T_A = +25^\circ\text{C}$ $T_A = -40^\circ$ to $+85^\circ\text{C}$	16	I_D	– – – –	– – 1.7 –	1.4 1.6 2.4 2.6	mA

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AC ELECTRICAL CHARACTERISTICS ($V_{CC} = +15\text{ V}$, $V_{EE} = -15\text{ V}$, $T_A = 25^\circ\text{C}$, unless otherwise noted.)

Characteristics	Figure	Symbol	Min	Typ	Max	Unit
Slew Rate ($V_{in} = -10\text{ V}$ to $+10\text{ V}$, $R_L = 2.0\text{ k}\Omega$, $C_L = 100\text{ pF}$, $A_V = +1.0\text{ V}$)	17, 32	SR	1.2	2.0	–	V/ μs
Gain Bandwidth Product ($f = 100\text{ kHz}$)	18	GBW	2.5	5.0	–	MHz
AC Voltage Gain ($R_L = 600\ \Omega$, $V_O = 0\text{ V}$, $f = 20\text{ kHz}$)	19, 20	A_{VO}	–	50	–	dB
Unity Gain Bandwidth (Open-Loop) ($R_L = 600\ \Omega$, $C_L = 0\text{ pF}$)		BW	–	3.0	–	MHz
Gain Margin ($R_L = 600\ \Omega$, $C_L = 0\text{ pF}$)	21, 23, 24	A_m	–	15	–	dB
Phase Margin ($R_L = 600\ \Omega$, $C_L = 0\text{ pF}$)	22, 23, 24	ϕ_m	–	60	–	Deg
Channel Separation ($f = 100\text{ Hz}$ to 20 kHz)	25	CS	–	-120	–	dB
Power Bandwidth ($V_O = 20\text{ V}_{pp}$, $R_L = 600\ \Omega$, $\text{THD} \leq 1.0\%$)		BW_p	–	32	–	kHz
Total Harmonic Distortion ($R_L = 600\ \Omega$, $V_O = 2.0\text{ V}_{pp}$, $A_V = +1.0\text{ V}$) ($f = 1.0\text{ kHz}$) ($f = 10\text{ kHz}$) ($f = 20\text{ kHz}$)	26	THD	–	0.0024 0.014 0.024	–	%
Open Loop Output Impedance ($V_O = 0\text{ V}$, $f = 3.0\text{ MHz}$, $A_V = 10\text{ V}$)	27	$ Z_O $	–	150	–	Ω
Differential Input Resistance ($V_{CM} = 0\text{ V}$)		R_{in}	–	200	–	k Ω
Differential Input Capacitance ($V_{CM} = 0\text{ V}$)		C_{in}	–	10	–	pF
Equivalent Input Noise Voltage ($R_S = 100\ \Omega$) $f = 10\text{ Hz}$ $f = 1.0\text{ kHz}$	28	e_n	–	8.0 7.5	–	nV/ $\sqrt{\text{Hz}}$
Equivalent Input Noise Current $f = 10\text{ Hz}$ $f = 1.0\text{ kHz}$	29	i_n	–	0.33 0.15	–	pA/ $\sqrt{\text{Hz}}$

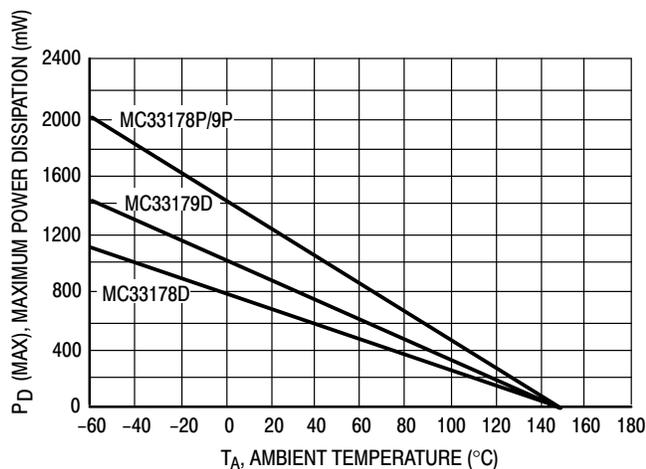


Figure 2. Maximum Power Dissipation versus Temperature

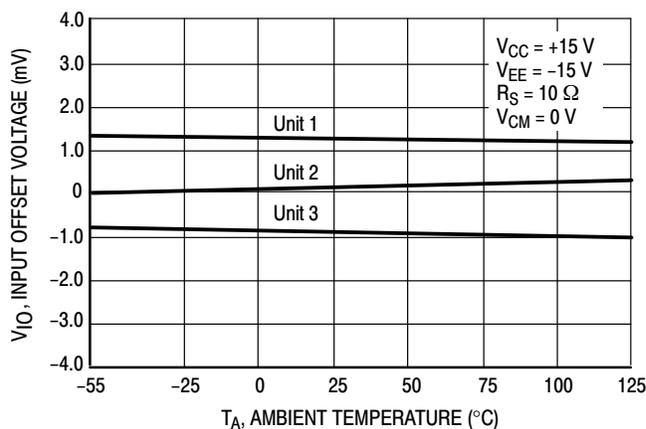


Figure 3. Input Offset Voltage versus Temperature for 3 Typical Units

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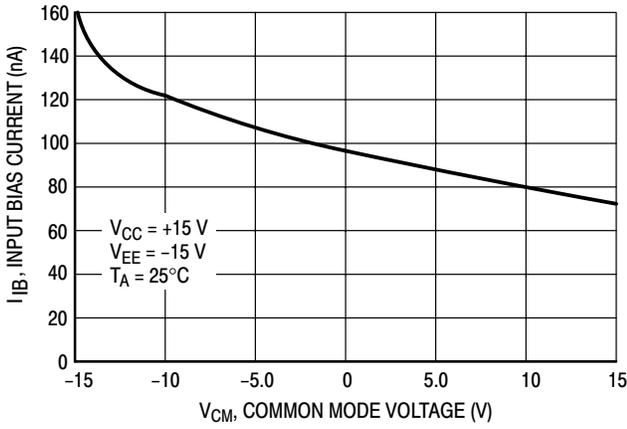


Figure 4. Input Bias Current versus Common Mode Voltage

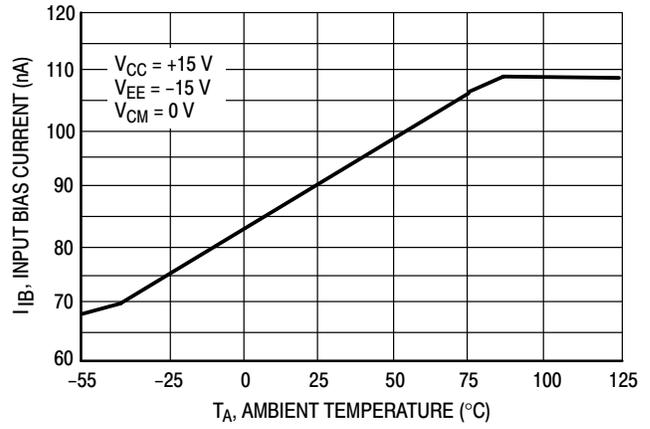


Figure 5. Input Bias Current versus Temperature

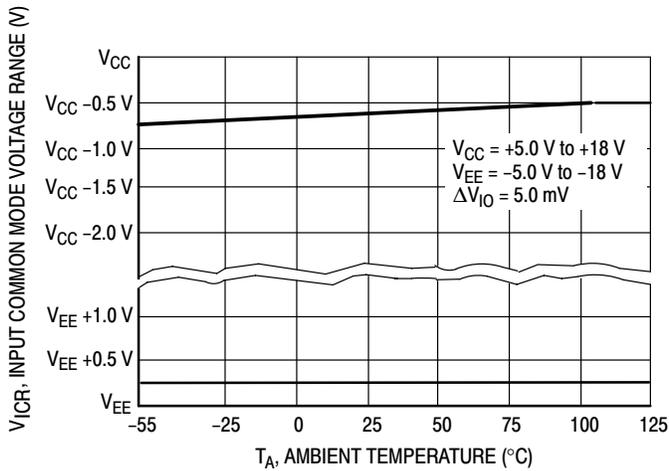


Figure 6. Input Common Mode Voltage Range versus Temperature

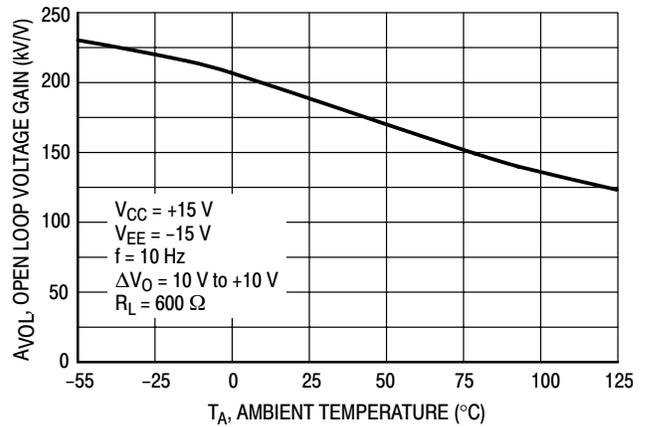


Figure 7. Open Loop Voltage Gain versus Temperature

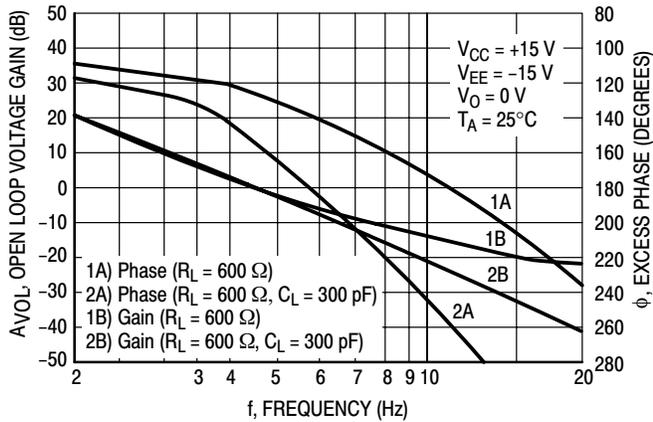


Figure 8. Voltage Gain and Phase versus Frequency

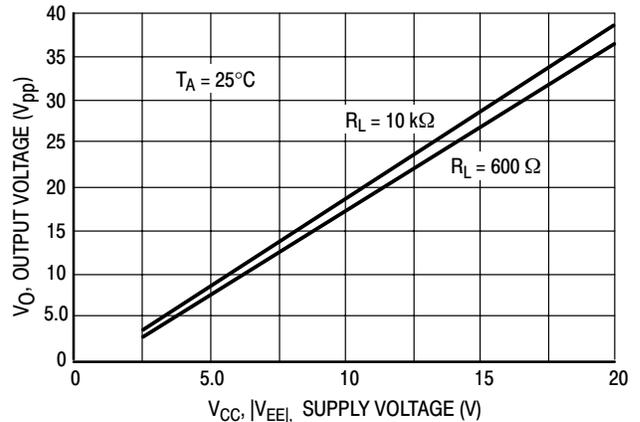


Figure 9. Output Voltage Swing versus Supply Voltage

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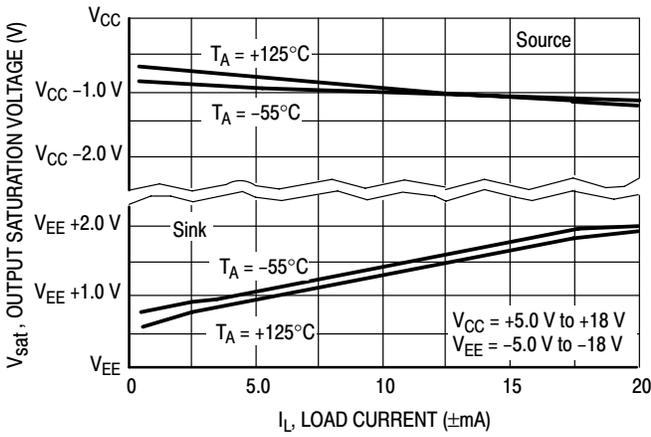


Figure 10. Output Saturation Voltage versus Load Current

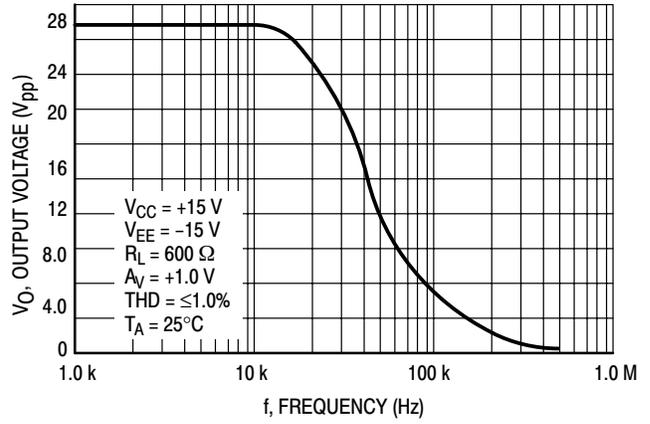


Figure 11. Output Voltage versus Frequency

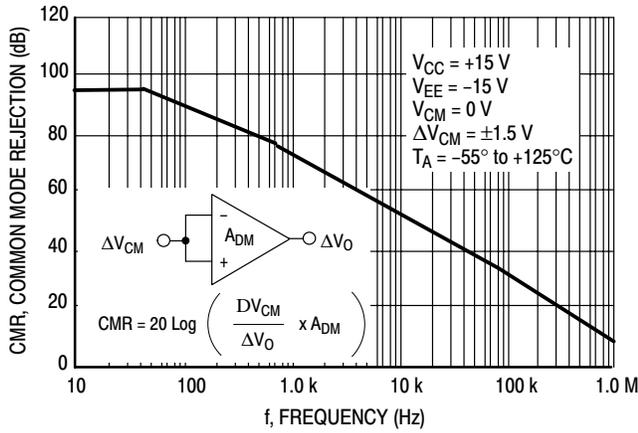


Figure 12. Common Mode Rejection versus Frequency Over Temperature

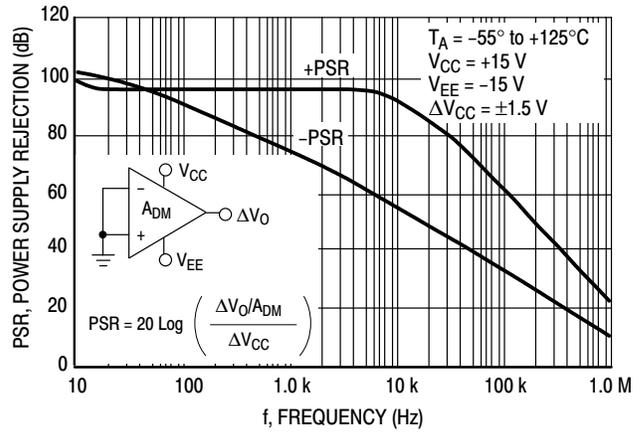


Figure 13. Power Supply Rejection versus Frequency Over Temperature

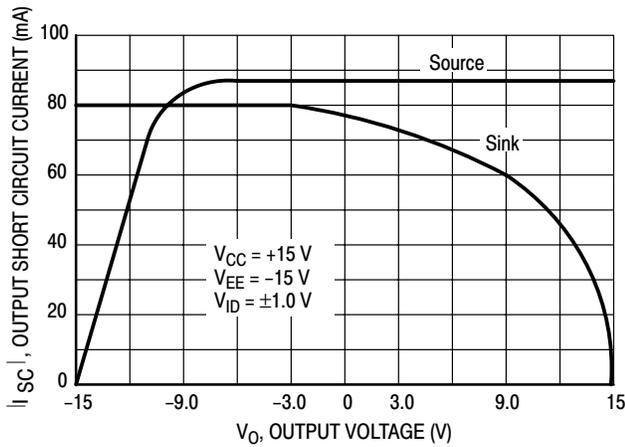


Figure 14. Output Short Circuit Current versus Output Voltage

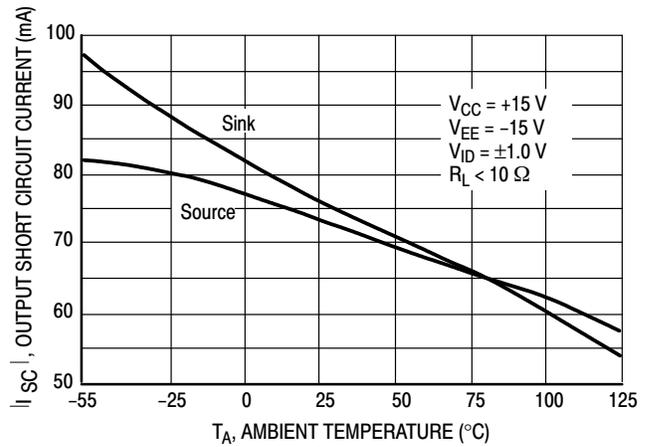


Figure 15. Output Short Circuit Current versus Temperature

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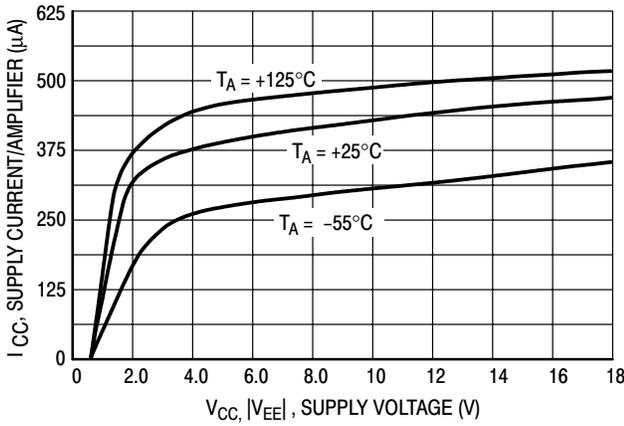


Figure 16. Supply Current versus Supply Voltage with No Load

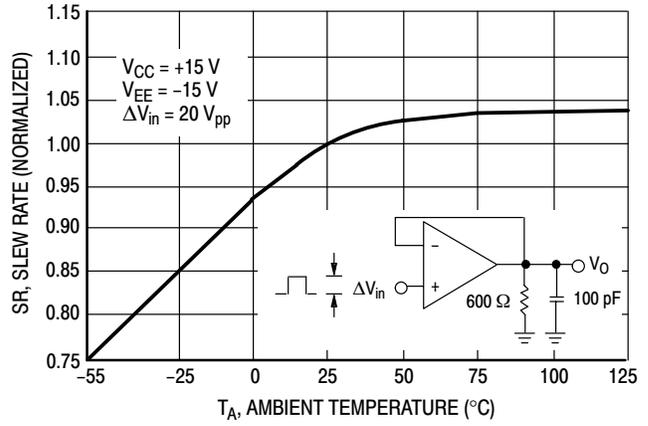


Figure 17. Normalized Slew Rate versus Temperature

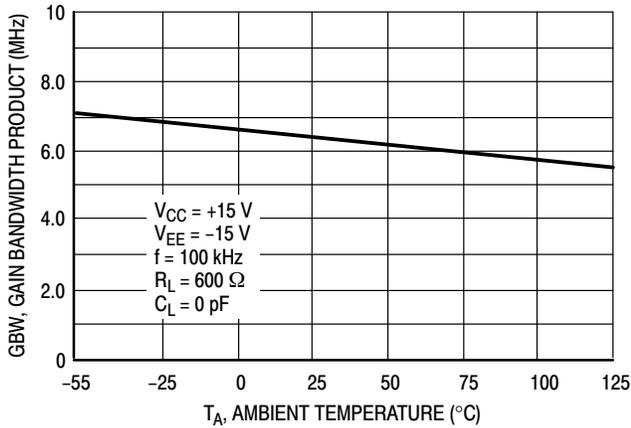


Figure 18. Gain Bandwidth Product versus Temperature

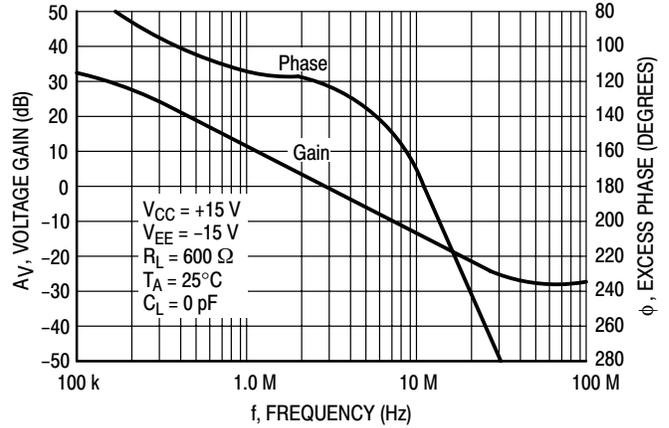


Figure 19. Voltage Gain and Phase versus Frequency

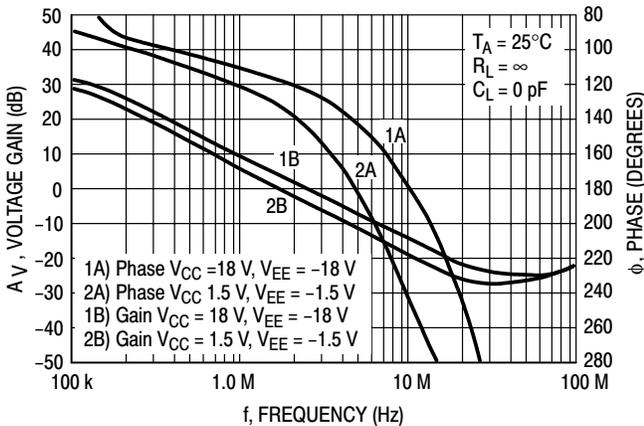


Figure 20. Voltage Gain and Phase versus Frequency

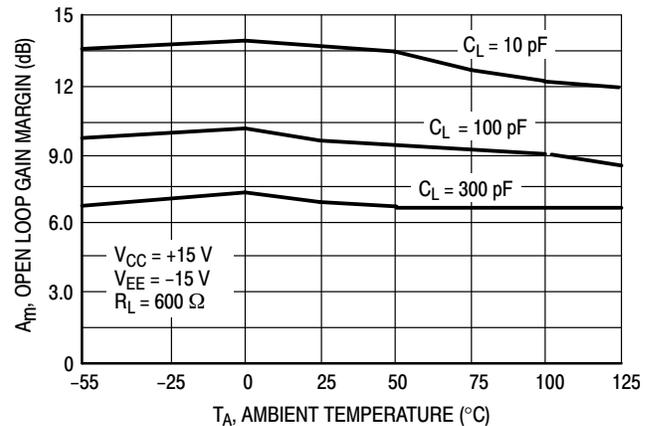


Figure 21. Open Loop Gain Margin versus Temperature

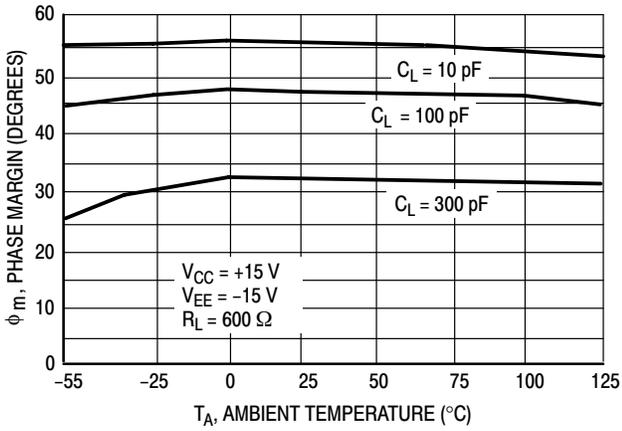


Figure 22. Phase Margin versus Temperature

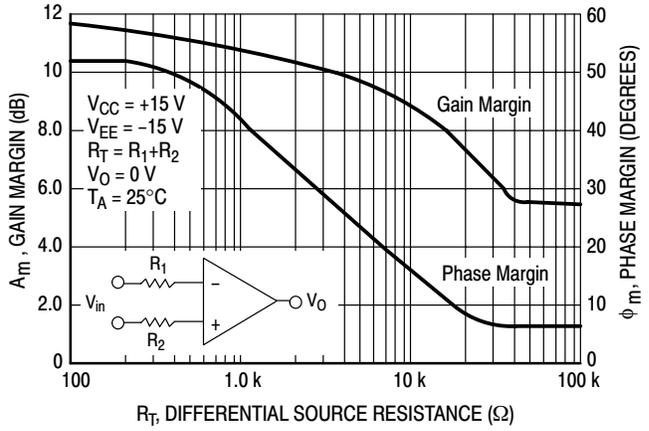


Figure 23. Phase Margin and Gain Margin versus Differential Source Resistance

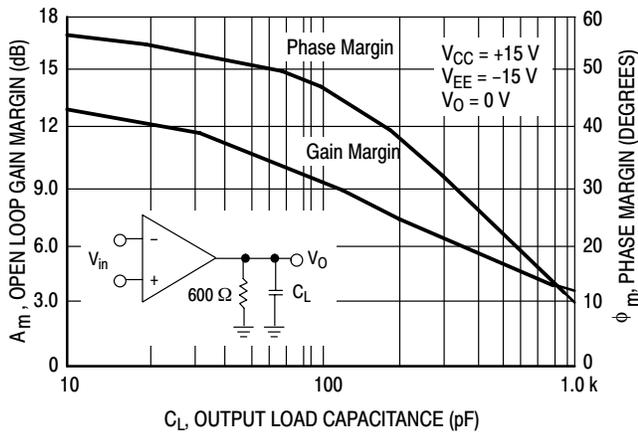


Figure 24. Open Loop Gain Margin and Phase Margin versus Output Load Capacitance

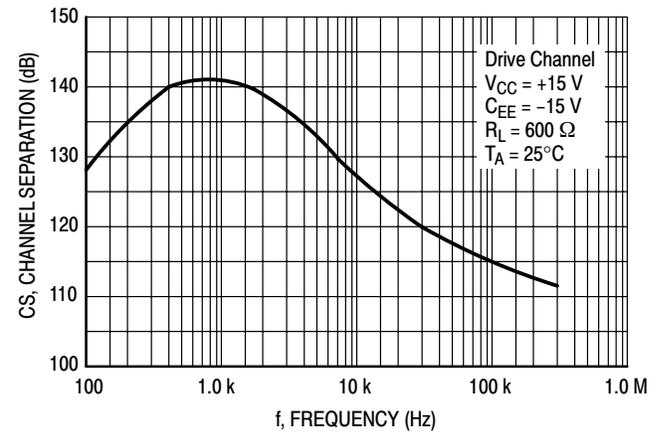


Figure 25. Channel Separation versus Frequency

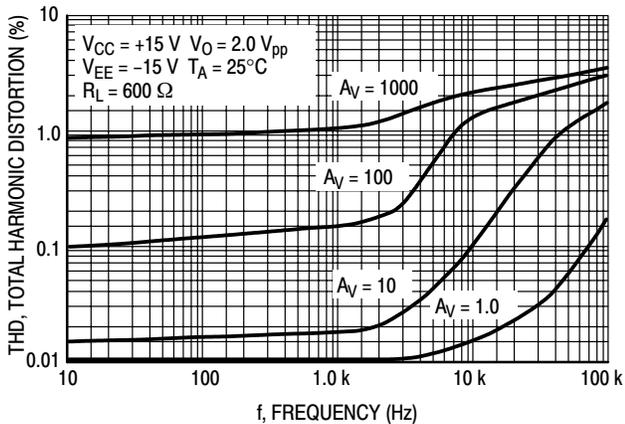


Figure 26. Total Harmonic Distortion versus Frequency

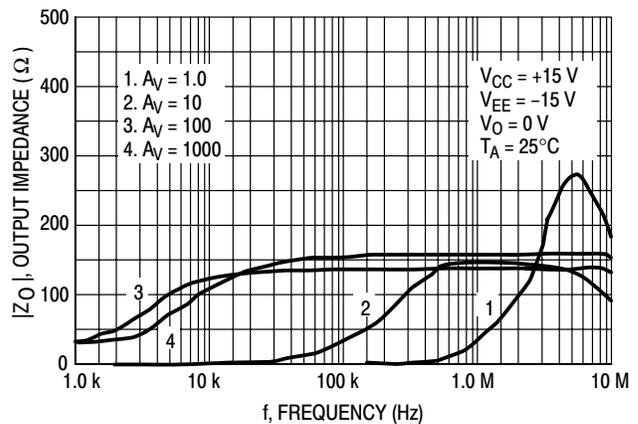


Figure 27. Output Impedance versus Frequency

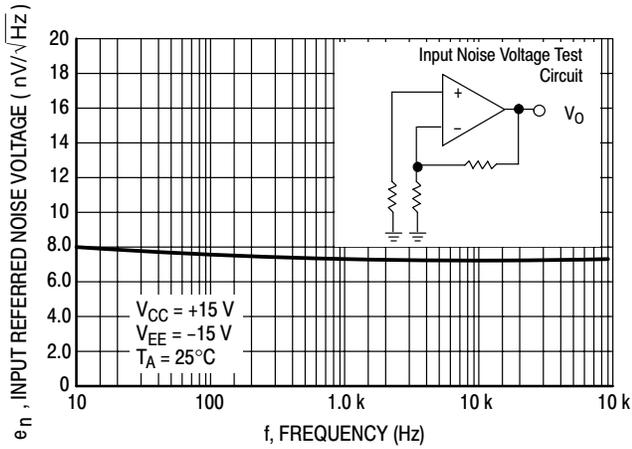


Figure 28. Input Referred Noise Voltage versus Frequency

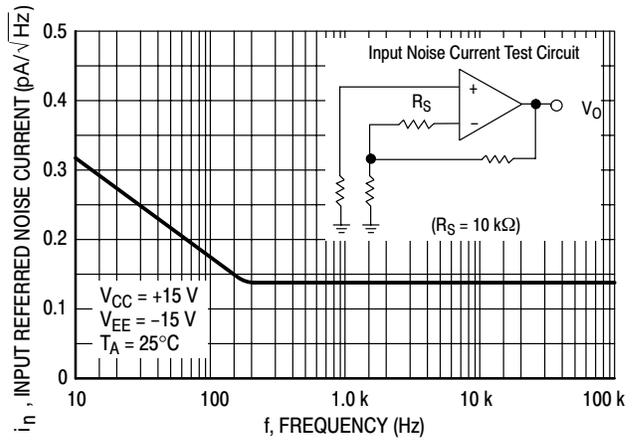


Figure 29. Input Referred Noise Current versus Frequency

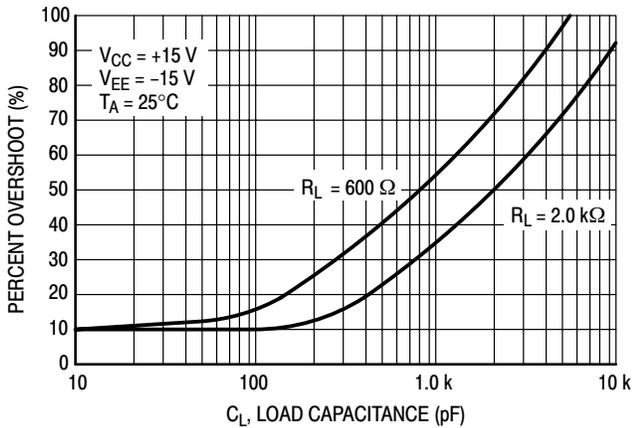


Figure 30. Percent Overshoot versus Load Capacitance

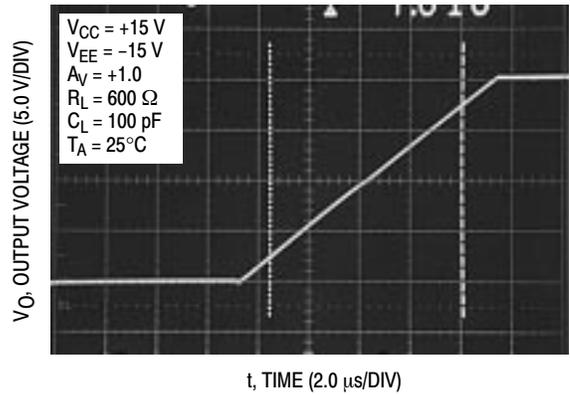


Figure 31. Non-inverting Amplifier Slew Rate

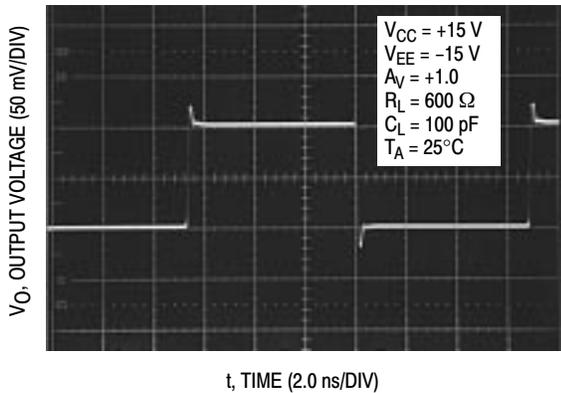


Figure 32. Small Signal Transient Response

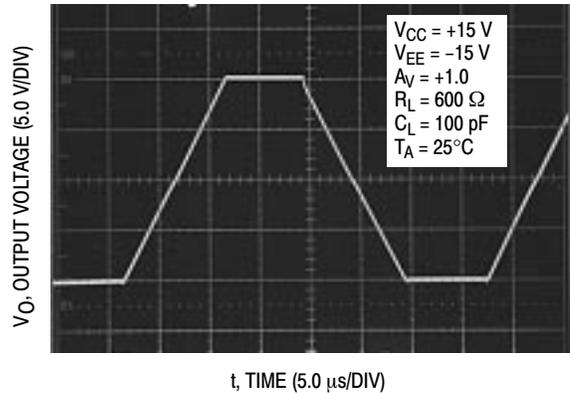


Figure 33. Large Signal Transient Response

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If a high source of resistance is used ($R_1 > 1.0 \text{ k}\Omega$), a compensation capacitor equal to or greater than the input capacitance of the op amp (10 pF) placed across the feedback resistor (see Figure 35) can be used to neutralize that pole and prevent outer loop oscillation. Since the closed loop transient response will be a function of that capacitance, it is important to choose the optimum value for that capacitor. This can be determined by the following Equation:

$$C_C = (1 + [R_1/R_2])^2 \times C_L (Z_O/R_2) \quad (1)$$

where: Z_O is the output impedance of the op amp.

For moderately high capacitive loads ($500 \text{ pF} < C_L < 1500 \text{ pF}$) the addition of a compensation resistor on the order of 20Ω between the output and the feedback loop will help to decrease miller loop oscillation (see Figure 36). For high capacitive loads ($C_L > 1500 \text{ pF}$), a combined compensation scheme should be used (see Figure 37). Both the compensation resistor and the compensation capacitor affect the transient response and can be calculated for optimum performance. The value of C_C can be calculated using Equation (1). The Equation to calculate R_C is as follows:

$$R_C = Z_O \times R_1/R_2 \quad (2)$$

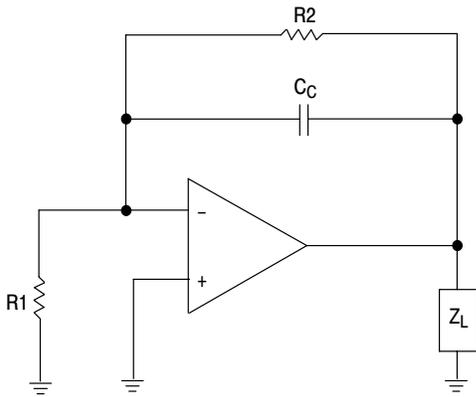


Figure 35. Compensation for High Source Impedance

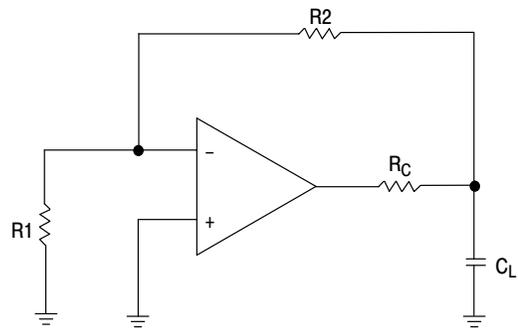


Figure 36. Compensation Circuit for Moderate Capacitive Loads

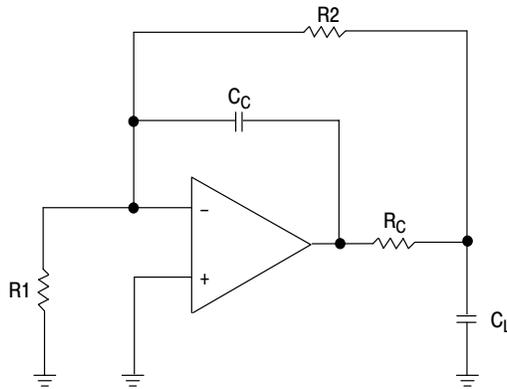
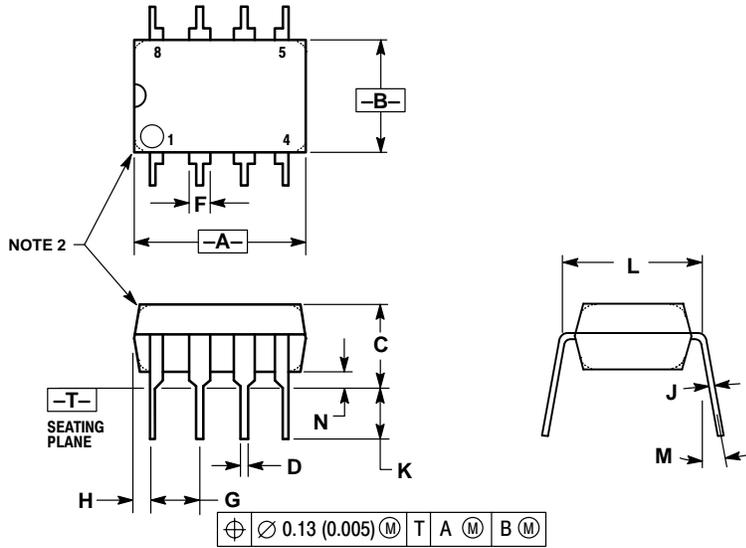


Figure 37. Compensation Circuit for High Capacitive Loads

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PACKAGE DIMENSIONS

PDIP-8
P SUFFIX
CASE 626-05
ISSUE L

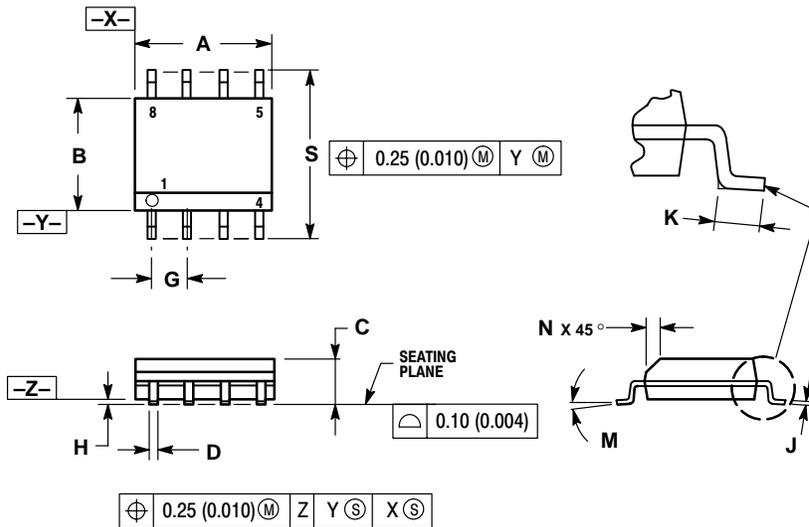


NOTES:

1. DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.
2. PACKAGE CONTOUR OPTIONAL (ROUND OR SQUARE CORNERS).
3. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	9.40	10.16	0.370	0.400
B	6.10	6.60	0.240	0.260
C	3.94	4.45	0.155	0.175
D	0.38	0.51	0.015	0.020
F	1.02	1.78	0.040	0.070
G	2.54 BSC		0.100 BSC	
H	0.76	1.27	0.030	0.050
J	0.20	0.30	0.008	0.012
K	2.92	3.43	0.115	0.135
L	7.62 BSC		0.300 BSC	
M	---	10°	---	10°
N	0.76	1.01	0.030	0.040

SO-8
D SUFFIX
CASE 751-07
ISSUE W



NOTES:

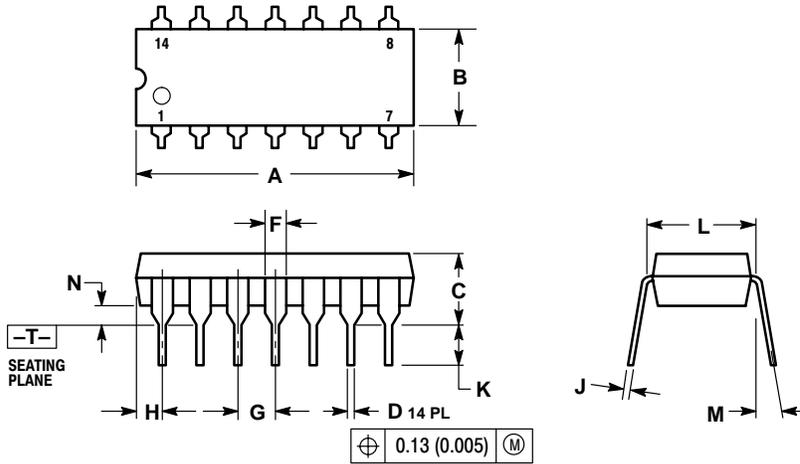
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETER.
3. DIMENSION A AND B DO NOT INCLUDE MOLD PROTRUSION.
4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	4.80	5.00	0.189	0.197
B	3.80	4.00	0.150	0.157
C	1.35	1.75	0.053	0.069
D	0.33	0.51	0.013	0.020
G	1.27 BSC		0.050 BSC	
H	0.10	0.25	0.004	0.010
J	0.19	0.25	0.007	0.010
K	0.40	1.27	0.016	0.050
M	0°	8°	0°	8°
N	0.25	0.50	0.010	0.020
S	5.80	6.20	0.228	0.244

MC33178, MC33179

PACKAGE DIMENSIONS

PDIP-14
P SUFFIX
CASE 646-06
ISSUE M

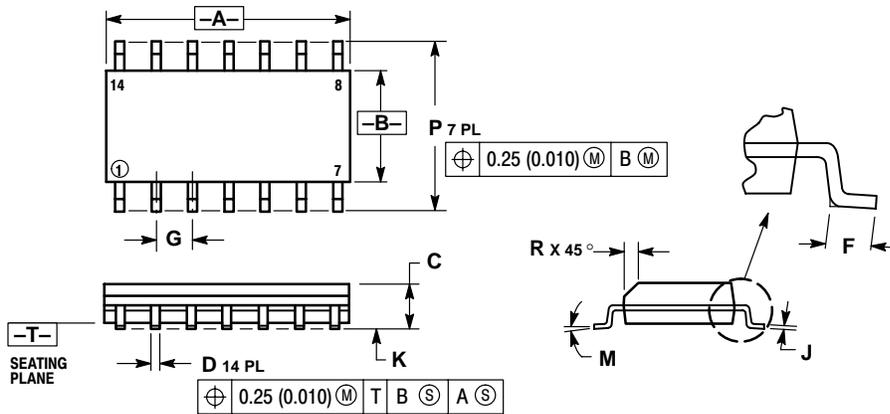


NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
5. ROUNDED CORNERS OPTIONAL.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.715	0.770	18.16	18.80
B	0.240	0.260	6.10	6.60
C	0.145	0.185	3.69	4.69
D	0.015	0.021	0.38	0.53
F	0.040	0.070	1.02	1.78
G	0.100 BSC		2.54 BSC	
H	0.052	0.095	1.32	2.41
J	0.008	0.015	0.20	0.38
K	0.115	0.135	2.92	3.43
L	0.290	0.310	7.37	7.87
M	---	10°	---	10°
N	0.015	0.039	0.38	1.01

SO-14
D SUFFIX
CASE 751A-03
ISSUE F



NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETER.
3. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	8.55	8.75	0.337	0.344
B	3.80	4.00	0.150	0.157
C	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27 BSC		0.050 BSC	
J	0.19	0.25	0.008	0.009
K	0.10	0.25	0.004	0.009
M	0°	7°	0°	7°
P	5.80	6.20	0.228	0.244
R	0.25	0.50	0.010	0.019

Notes

Notes

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